# Single commands

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| --- | --- |
| Command | Executes |
| 1 | Move to Area |
| 2 | Boost (to get on Area) |
|  |  |
| LEFT | Turn Left 90 |
| RIGHT | Turn Right 90 |
| UP | Move forward (untill sensors go off) |
| DOWN | Moves xxx sec backwards |
|  |  |
| BLUE | Turn Left 180 |
| YELLOW | Turn Right 180 |
| RED | Dodges the object |
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| GUIDE | Starts the process |
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# While moving

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| --- | --- |
| Command | Executes |
| OK / POWER1 | STOP |
| INFO | Shows sensor logs (in monitor with USB Cable) |
| CH+ | Stepper + 1 (turn right) |
| CH- | Stepper -1 (turn left) |
| VOL+ | Ducky Sensor Enabled |
| VOL- | Ducky Sensor Disabled |
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